

Smartrak Pipeline and Cable Tracker

SMARTRAK is the NEW Pipeline and Cable Tracking product family, designed and manufactured by Innovatum International in the UK.

SMARTRAK is smaller, lighter, uses less power and has more performance than previous magnetic pipeline and cable trackers.

SMARTRAK may be fitted to smaller vehicles than any other tracking system.

SMARTRAK uses automated calibration routines to improve performance and make operation simpler.

SMARTRAK is supplied in one wheeled case, ready to fit and run, complete with Tritech altimeter, all cables and a laptop PC.

SMARTRAK 3 – Passive Magnetic tracking only

SMARTRAK 6 – Tone tracking only

SMARTRAK 9 – Passive Magnetic and Tone tracking all in one unit

SIP & SENSOR MOUNTING

The SIP may be mounted in any orientation provided:

a) The long axis of the cylinder is horizontal or vertically up (connectors at top)

b) The long axis or arrow is aligned fore/aft or across the ROV

Sensors must be at least 70 cms in front of the ROV. Sensor separation should be around 60 to 90 cms between sensors.

Sensors must be vertical to within 1 degree, and the separation must be identical to within 1 mm. Sensors should be mounted around 20 – 50 cms above ROV skids.

Altimeter may be mounted in any convenient location.



INTERFACING INFORMATION

SMARTRAK SIP (Subsea Unit)

Length	24 cms
Diameter	19 cms
Weight in air	7 Kg
Weight in seawater approximate	3.8 Kg

SMARTRAK Sensors

Length overall	36 cms
Diameter	4 cms
Weight in air	1.1 Kg
Weight in seawater approximate	0.3 Kg

ROV Connector:

8 pin SUBCONN MCIL8F. Tail is provided with system

pin 1	RS232 down/ RS485 A
pin 2	RS232 common /RS485 B
pin 3	RS232 up
pin 4	Internal ground
pin 5	24 Vdc @850 mA
pin 6	24 Vdc return
pin 7	NC
pin 8	NC

Data link is bi-directional at 9600 baud. 232/485 is selected inside SIP by switches. RS485 is tested to 1.2 Km

Survey data output from surface PC is available.



Smartrak Performance

The following table gives **SMARTRAK** system performance as measured in a laboratory environment, and the estimated performance when installed on an ROV.

These performances are based on existing array configurations. New arrays are in test now, and significant performance gains will be available soon.

	System Alone	System on Vehicle **
1. Passive Pipe (Data only normally available for approximately 80% of pipelength)		
Tracking & Depth (+/- 25 cm)	4" dia 5 metres	3 metres
	16" dia 8 metres	6 metres
	48" dia 10 metres	7 metres
2. AC Tone Tracking Mode		
Detection	2.5 mA @ 2 metres	5 mA @ 2 metres
	40 mA @ 30 metres	80 mA @ 30 metres
Detection & Direction	5 mA @ 2 metres	10 mA @ 2 metres
Tracking & Depth (+/- 10 cm)	5 mA @ 1 metre	10 mA @ 1 metre
3. DC Current Tracking Mode		
Detection	0.4A @ 1.5 metre	0.4A @ 0.75 metre
	or 1.6A @ 3 metres	1.6A @ 1.5 metre
Detection & Direction	0.4A @ 0.75 metre	0.4A @ 0.5 metre
	or 1.6A @ 1.5 metre	1.6A @ 1 metre
Tracking & Depth (+/- 25cm)	0.4A @ 0.5 metre	0.4A @ 0.4 metre
	or 1.6A @ 1 metre	1.6A @ 0.8 metre
4. Passive Cable 25mm (Magnetised) Only cables with a steel wire content can be tracked passively		
Detection	5 metres	3 metres
Tracking (+/- 5 cm)	3 metres	2 metres
Tracking & Depth (+/- 5 cm)	2 metres	1.5 metres

** Vehicle AC noise estimated at 0.2 nanotesla at sensors

** Vehicle DC noise estimated at 20 nanotesla per foot at sensors)

Infield performance may be degraded due to local magnetic disturbances, vehicle noise, poor installation and incorrect operation